Completed as a **multi-output low-noise SMPS** for the SMILE satellite in **cooperation with ESA**, this PSU BreadBoad is currently at CDR level (TRL 5).

The design was completed according to specifications received from the customer to an existing space sector need.

Breadboard design was implemented using COTS components with Spacegrade substitutes and outlines in mind, so that the same card size can be achieved in the FM.

The SMPS was implemented with a forward architecture, using operating frequencies of:

- 180-220 kHz (synchronized)
- 165kHz (free-running)

The PSU also features a **magnetic feedback** with a free-running frequency of 2 MHz.

Compliance with standards:

- Derating: *ECSS-Q-ST-30-11C*
- CE of CM and DM Noise, Inrush current: *ECSS-E-ST-20-07C* (Subsystem and equipment limits)
- TMTC interfaces: ECSS-E-ST-50-14C

Output channel features:

- Overcurrent and overvoltage protection
- LDOs as a post-regulation
- CM filtering
- Dynamic preloads (for zero-load needs)

Input protections

- Under-voltage Lockout
- Optional input LCL (Overcurrent protection)

TMTC:

Digital TMTC

- ON/OFF commands according to HV/LV-HPC
- ON/OFF Status telemetry according to BSM
- An ON/OFF logic based on redundant telecommands and inner status (e.g. overcurrent/overvoltage signals)

Analogue TMTC

- PT1000 thermistors for temperature telemetry
- Galvanically isolated current telemetry (4-20mA interface)

FM radiation level: TID: 50 krad

Temperature range: [-30°C, +60°C]

<image>

Figure 1: EBB of the Incentive Scheme PSU



Table 1: Output parametes							
	Implemented parameters		Customizable parameters				
Channel	Nominal voltage	Maximum current	Minimum voltage	Maximum voltage			
Vmot_44Vp	44V	0.8A	3.3V	100V			
Vmot_44Vn	-44V	0.8A	3.3V	100V			
Vmot_15V	15V	0.15A	3.3V	100V			

Note 1: Maximum possible output power on the converters is 200 W.

Note 2: Voltages on the output can't be higher than the minimal input voltage x2.

Note 3: The Vmot_15V channel (as it has a very small current) was implemented using a fly-buck architecture. Maximal power like this is limited to 5W, but having a channel like this is not mandatory.

Table 2: Input bus parameters							
Versions	Implemented minimum voltage	Implemented nominal voltage	Implemented maximum voltage	Maximum viable voltage			
28V bus version	22V	28V	38V	400V			
50V bus version	32V	50V	52V	400V			

Note 1: An input voltage range should have a smaller range (Maximal voltage/Minimal voltage) than a factor of 2 for an efficient design.



